

Materiales usados

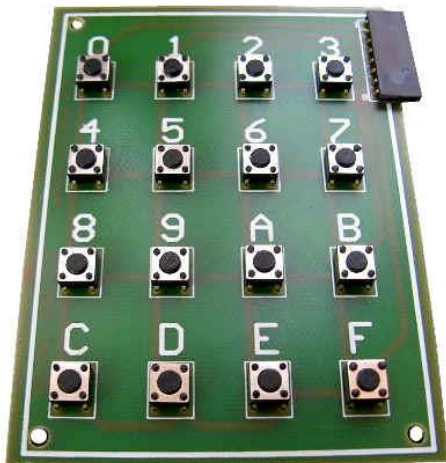
Módulo driver de motor a pasos ULN2003



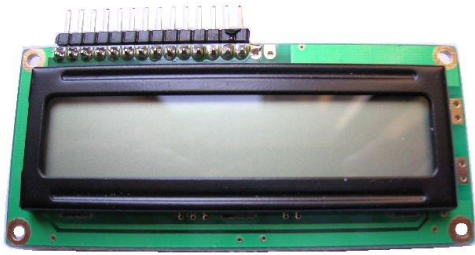
Motor a pasos unipolar 28BYJ-48



Teclado hexadecimal matricial de 4x4



Display LCD 16x1



Jumpers hembra-macho



Sistema microcontrolador BOLT 18F2550

